Contents – Volume V

1 Integrated Cantilevers and Atomic Force Microscopes
Sadik Hafizovic, Kay-Uwe Kirstein, Andreas Hierlemann 1

1.1 Overview 1

1.2 Active Cantilevers 2
1.2.1 Integrated Force Sensor 4
1.2.2 Integrated Actuation 8

1.3 System Integration 10
1.3.1 Analog Signal Processing and Conditioning 10
1.3.2 Digital Signal Processing 13

1.4 Single-Chip CMOS AFM 16
1.4.1 Measurements 19

1.5 Parallel Scanning 19

1.6 Outlook 21

References 21

2 Electrostatic Microscanner
Yasuhisa Ando 23

2.1 Introduction 23

2.2 Displacement Conversion Mechanism 24
2.2.1 Basic Conception 24
2.2.2 Combination with Comb Actuator 25
2.2.3 Various Types of Displacement Conversion Mechanism 27

2.3 Design, Fabrication Technique, and Performance 29
2.3.1 Main Structure of 3D Microstage 29
2.3.2 Amplification Mechanism of Scanning Area 31
2.3.3 Fabrication Using ICP-RIE 34
2.3.4 Evaluation of Motion of 3D Microstage 37

2.4 Applications to AFM 39
2.4.1 Operation by Using Commercial Controller 39

2.4.2 Evaluation of Microscanner Using Grating Image 41
2.4.3 SPM Operation Using Microscanner 45

References 49

3 Low-Noise Methods for Optical Measurements of Cantilever Deflections
Tilman E. Schäffer 51

3.1 Introduction 51

3.2 The Optical Beam Deflection Method 52
3.2.1 Gaussian Optics 52
3.2.2 Detection Sensitivity 54

3.3 Optical Detection Noise 55
3.3.1 Noise Sources 55
3.3.2 Shot Noise 55

3.4 The Array Detector 56

3.5 Dynamic Range and Linearity 59
3.5.1 The Two-Segment Detector 59
3.5.2 The Array Detector 61

3.6 Detection of Higher-Order Cantilever Vibration Modes 62
3.6.1 Normal Vibration Modes 63
3.6.2 Optimization of the Detection Sensitivity 64

3.7 Calculation of Thermal Vibration Noise 66
3.7.1 Focused Optical Spot of Infinitesimal Size 66
3.7.2 Focused Optical Spot of Finite Size 67

3.8 Thermal Spring Constant Calibration 69

References 70

4 *Q*-controlled Dynamic Force Microscopy in Air and Liquids
Hendrik Hölscher, Daniel Ebeling, Udo D. Schwarz 75

4.1 Introduction 75

4.2 Theory of *Q*-controlled Dynamic Force Microscopy 76
4.2.1 Equation of Motion of a Dynamic Force Microscope with *Q*-control 76
4.2.2 Active Modification of the *Q*-factor 78
4.2.3 Including Tip–Sample Interactions 80
4.2.4 Prevention of Instabilities by *Q*-control in Air 82
4.2.5 Reduction of Tip–Sample Indentation and Force by *Q*-control in Liquids 86

4.3 Experimental Applications of *Q*-control 89

4.3.1 Examples for Q-control Applications in Ambient Conditions . . . 90
4.4 Summary . . . 94
References . . . 95

5 High-Frequency Dynamic Force Microscopy
Hideki Kawakatsu . . . 99

5.1 Introduction . . . 99
5.2 Instrumental . . . 99
5.2.1 Cantilever . . . 99
5.2.2 Detection . . . 102
5.2.3 Excitation . . . 105
5.2.4 Circuitry . . . 106
5.3 Experimental . . . 107
5.3.1 Low-Amplitude Operation . . . 107
5.3.2 Manipulation . . . 108
5.3.3 Atomic-Resolution Lateral Force Microscopy . . . 108
5.3.4 Other Techniques for High Frequency Motion Detection . . . 108
5.4 Summary and Outlook . . . 109
References . . . 110

6 Torsional Resonance Microscopy and Its Applications
Chanmin Su, Lin Huang, Craig B. Prater, Bharat Bhushan . . . 113

6.1 Introduction to Torsional Resonance Microscopy . . . 113
6.2 TRmode System Configuration . . . 115
6.3 Torsional Modes of Oscillation . . . 119
6.4 Imaging and Measurements with TRmode . . . 123
6.4.1 TRmode in Weakly-Coupled Interaction Region . . . 123
6.4.2 TRmode Imaging and Measurement in Contact Mode . . . 127
6.5 Applications of TRmode Imaging . . . 129
6.5.1 High-Resolution Imaging Application . . . 129
6.5.2 Electric Measurements Under Controlled Proximity by TRmode . . . 132
6.5.3 In-Plane Anisotropy . . . 138
6.6 Torsional Tapping Harmonics for Mechanical Property Characterization . . . 140
6.6.1 Detecting Cantilever Harmonics Through Torsional Detection . . . 142
6.6.2 Reconstruction of Time-Resolved Forces . . . 142
6.6.3 Force-Versus-Distance Curves . . . 143
6.6.4 Mechanical Property Measurements and Compositional Mapping . . . 144

6.7 Conclusion 145
References 146

7 Modeling of Tip-Cantilever Dynamics in Atomic Force Microscopy
Yaxin Song, Bharat Bhushan 149

7.1 Introduction 155
7.1.1 Various AFM Modes and Measurement Techniques 155
7.1.2 Models for AFM Cantilevers 161
7.1.3 Outline 163
7.2 Modeling of AFM Tip-Cantilever Systems in AFM 163
7.2.1 Tip–Sample Interaction 164
7.2.2 Point-Mass Model 166
7.2.3 The 1D Beam Model 168
7.2.4 Pure Torsional Analysis of TRmode 171
7.2.5 Coupled Torsional-Bending Analysis 177
7.3 Finite Element Modeling of Tip-Cantilever Systems 187
7.3.1 Finite Element Beam Model of Tip-Cantilever Systems 188
7.3.2 Modeling of TappingMode 192
7.3.3 Modeling of Torsional Resonance Mode 196
7.3.4 Modeling of Lateral Excitation Mode 199
7.4 Atomic-Scale Topographic and Friction Force Imaging in FFM . . 200
7.4.1 FFM Images of Graphite Surface 202
7.4.2 Interatomic Forces Between Tip and Surface 204
7.4.3 Modeling of FFM Profiling Process 205
7.4.4 Simulations on Graphite Surface 208
7.5 Quantitative Evaluation of the Sample's Mechanical Properties . . 213
7.6 Closure 216
A Appendices 217
A.1 Stiffness and Mass Matrices of 3D Beam Element 217
A.2 Mass Matrix of the Tip 218
A.3 Additional Stiffness and Mass Matrices Under Linear Tip–Sample Interaction 219
References 220

8 Combined Scanning Probe Techniques for In-Situ Electrochemical Imaging at a Nanoscale
Justyna Wiedemair, Boris Mizaikoff, Christine Kranz 225

8.1 Overview 227
8.2 Combined Techniques 228

8.2.1 Integration of Electrochemical Functionality 230
8.2.2 Combined Techniques Based on Force Interaction 231
8.2.3 Combined Techniques Based on Tunneling Current 232
8.2.4 Combined Techniques Based on Optical Near-Field Interaction . . 233
8.2.5 Theory 234
8.2.6 Combined Probe Fabrication 234

8.3 Applications 243
8.3.1 Model Systems 244
8.3.2 Imaging Enzyme Activity 246
8.3.3 AFM Tip-Integrated Biosensors 249
8.3.4 Combined SPM for Imaging of Living Cells 253
8.3.5 Measurement of Local pH Changes 255
8.3.6 Corrosion Studies 257

8.4 Outlook: Further Aspects of Multifunctional Scanning Probes . . . 259

References 261

9 New AFM Developments to Study Elasticity and Adhesion at the Nanoscale
Robert Szoszkiewicz, Elisa Riedo 269

9.1 Introduction 270

9.2 Contact Mechanics Theories and Their Limitations 271

9.3 Modulated Nanoindentation 273
9.3.1 Force-Indentation Curves 273
9.3.2 Elastic Moduli 276

9.4 Ultrasonic Methods at Local Scales 278
9.4.1 Brief Description of Ultrasonic Methods 278
9.4.2 Applications of Ultrasonic Techniques in Elasticity Mapping . . . 281
9.4.3 UFM Measurements of Adhesion Hysteresis and Their Relations to Friction at the Tip-Sample Contact 282

References 284

10 Near-Field Raman Spectroscopy and Imaging
Pietro Giuseppe Gucciardi, Sebastiano Trusso, Cirino Vasi, Salvatore Patanè, Maria Allegrini 287

10.1 Introduction 287

10.2 Raman Spectroscopy 289
10.2.1 Classical Description of the Raman Effect 289
10.2.2 Quantum Description of the Raman Effect 291
10.2.3 Coherent Anti-Stokes Raman Scattering 295

10.2.4 Experimental Techniques in Raman Spectroscopy 296

10.3 Near-Field Raman Spectroscopy 299
10.3.1 Theoretical Principles of the Near-Field Optical Microscopy 300
10.3.2 Setups for Near-Field Raman Spectroscopy 302

10.4 Applications of Near-Field Raman Spectroscopy 306
10.4.1 Structural Mapping 307
10.4.2 Chemical Mapping 312
10.4.3 Probing Single Molecules by Surface-Enhanced and Tip-Enhanced Near-Field Raman Spectroscopy 314
10.4.4 Near-Field Raman Spectroscopy and Imaging of Carbon Nanotubes 321
10.4.5 Coherent Anti-Stokes Near-Field Raman Imaging 324

10.5 Conclusions 326

References 326

Subject Index 331